



Superior Clamping and Gripping



Product Information

Universal gripper JGP 40

Loadable. Reliable. Compact.

Universal gripper JGP

Universal 2-finger parallel gripper of the compact class with T-slot guidance and best cost-performance ratio

Field of application

Optimum standard solution for many fields of application. Universal application in clean and slightly dirty surroundings in machine building and plant building industry, assembly and handling as well as automotive industry.

Advantages – Your benefits

A firm focus on the essentials for maximum profitability

Sturdy T-slot guidance for the precise handling of different workpieces

Compact dimensions and low weight for minimal interfering contours in handling

High maximum moments possible suitable for using long gripper fingers

Wedge-hook design for high power transmission and synchronized gripping

Comprehensive sensor accessories for monitoring and control of the stroke position

Mounting from two gripper sides for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems



Sizes
Quantity: 10



Weight
0.08 .. 17.5 kg



Gripping force
123 .. 7400 N



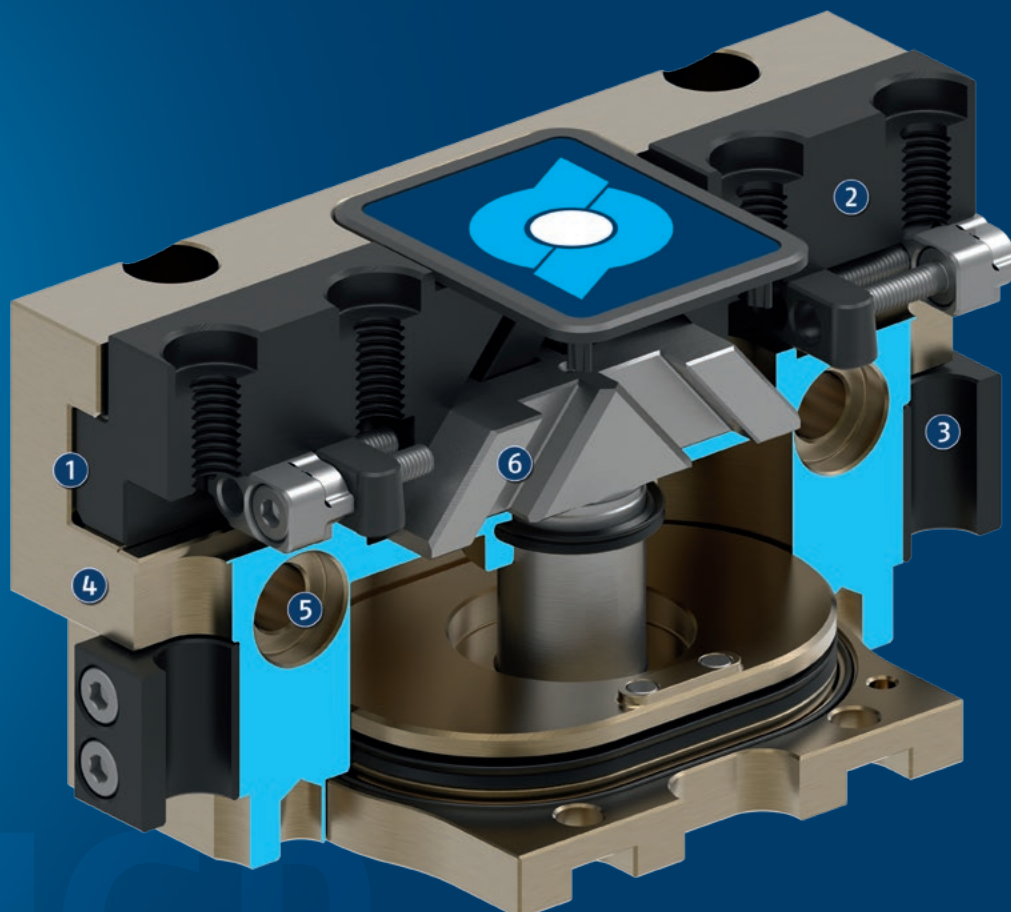
Stroke per jaw
2 .. 35 mm



Workpiece weight
0.62 .. 30 kg

Functional description

The oval piston is moved up or down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, parallel jaw motion.



- ① **T-slot guidance**
loadable, robust base jaw guidance for extremely long gripper fingers
- ② **Base Jaw**
for the connection of workpiece-specific gripper fingers
- ③ **Sensor system**
Proximity switch can be assembled without mounting kit

- ④ **Housing**
is weight-optimized due to the use of high-strength aluminum alloy
- ⑤ **Centering and mounting possibilities**
for universal assembly of the gripper
- ⑥ **Wedge-hook design**
for high force transmission and centric gripping

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

Scope of delivery: Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

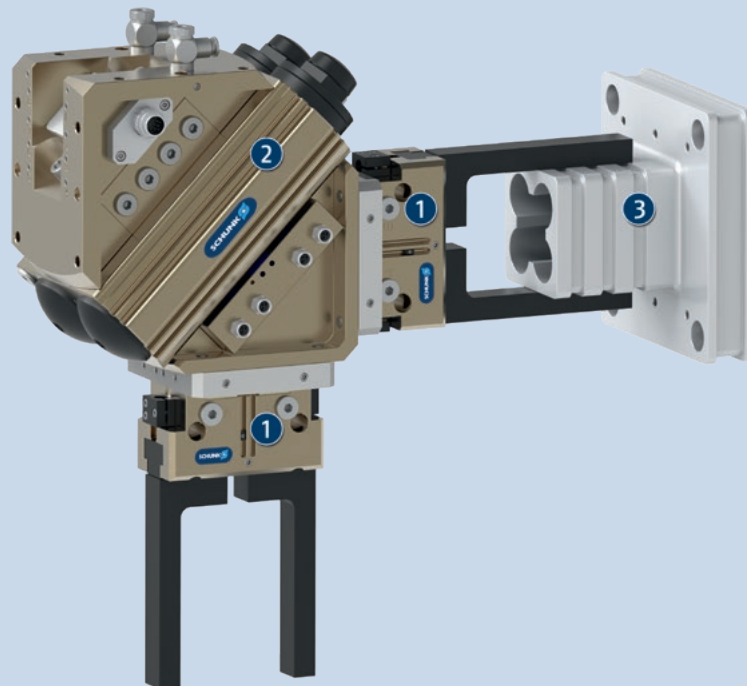
Finger length: is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.



Application example

Swivel head with double parallel gripper for simultaneous loading and unloading of workpieces in a machine.

① 2-finger parallel gripper JGP with workpiece-specific gripper fingers

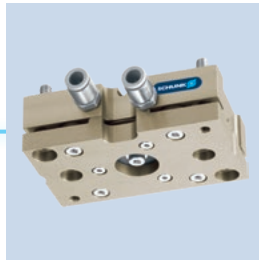
② Swivel head SRH-plus
③ Workpiece

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Compensation unit



Tolerance compensation unit



Manual change system



Pressure maintenance valve



Analog position sensor



Finger blank



Jaw quick-change system



Universal intermediate jaw



Flexible position sensor



Magnetic switches



Inductive proximity switches

① For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

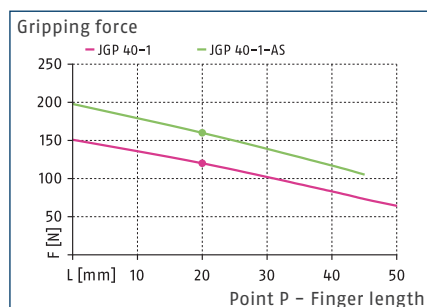
Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

The JGP series is especially suitable for economic handling solutions and distinguishes by its high cost-benefit ratio.

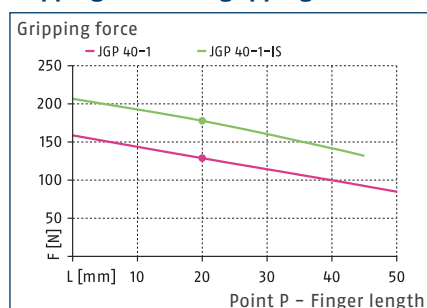
Integrated air purge connection: impedes the ingress of dirt into the inside of the gripper



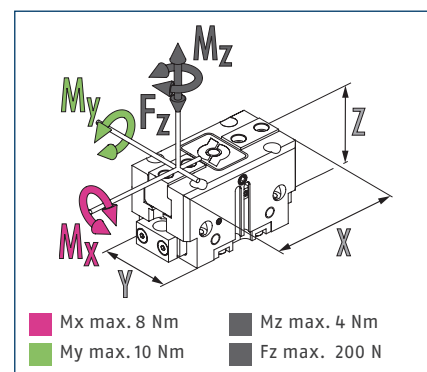
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



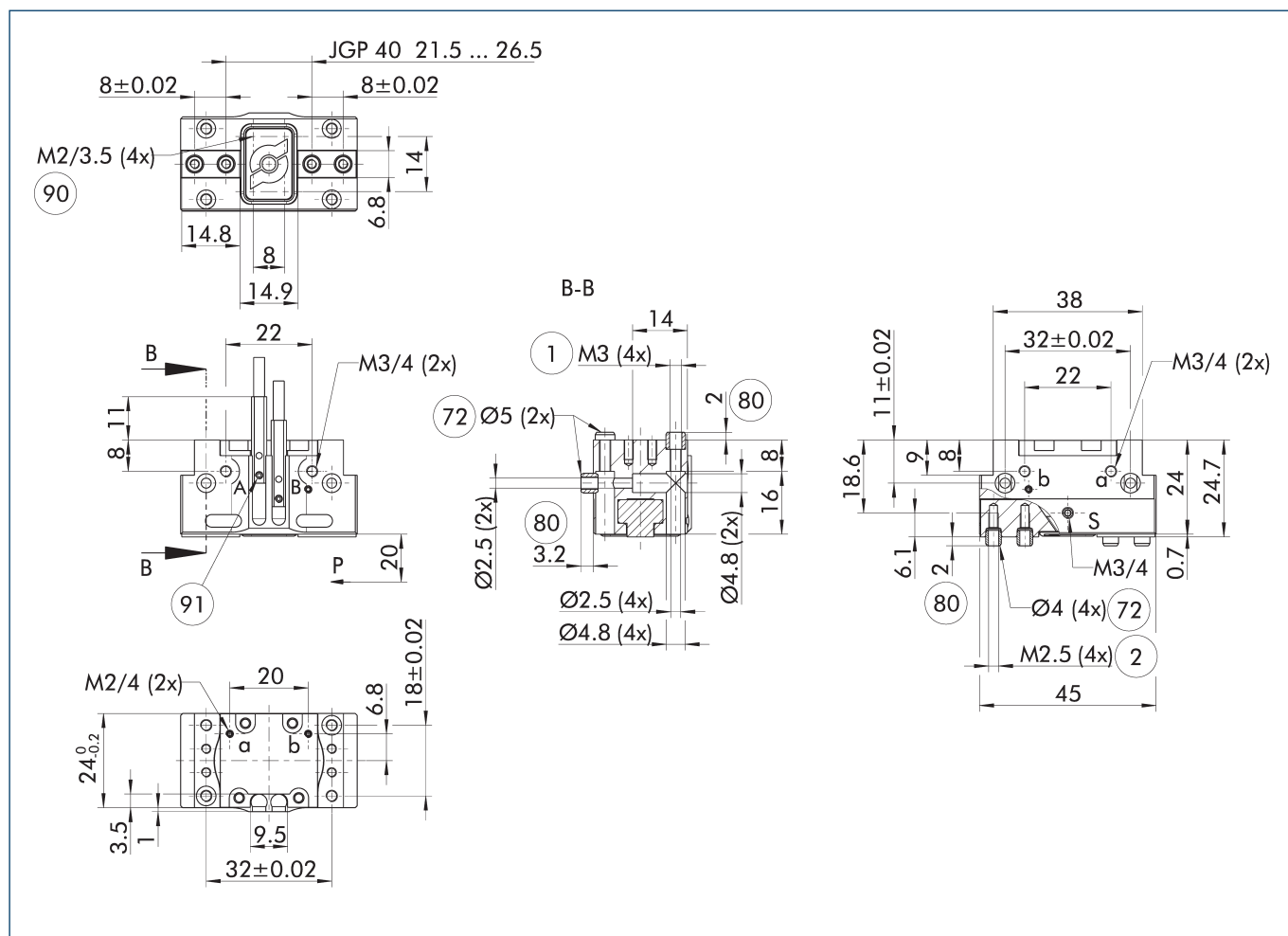
① The indicated moments and forces are static values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		JGP 40	JGP 40-AS	JGP 40-IS
ID		0308600	0308601	0308602
Stroke per jaw	[mm]	2.5	2.5	2.5
Closing/opening force	[N]	123/132	163/-	-/182
Min. spring force	[N]		40	50
Weight	[kg]	0.08	0.09	0.09
Recommended workpiece weight	[kg]	0.62	0.62	0.62
Fluid consumption double stroke	[cm³]	2.5	4.5	5.5
Min./nom./max. operating pressure	[bar]	2.5/6/8	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.5/1	0.5/1	0.5/1
Closing/opening time	[s]	0.02/0.02	0.02/0.03	0.03/0.02
Closing/opening time with spring	[s]		0.05	0.05
Max. permissible finger length	[mm]	50	45	45
Max. permissible mass per finger	[kg]	0.1	0.1	0.1
IP protection class		40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01
Dimensions X x Y x Z	[mm]	45 x 25 x 24.6	45 x 25 x 33.75	45 x 25 x 33.75

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

- ① The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).

A, a Main / direct connection, gripper opening

B, b Main / direct connection, gripper closing

S Air purge connection

① Gripper connection

② Finger connection

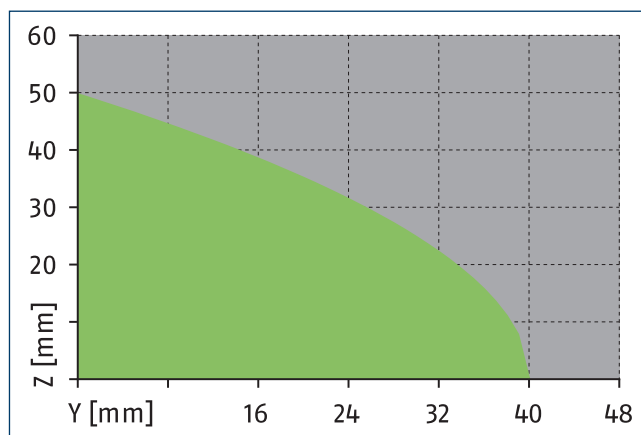
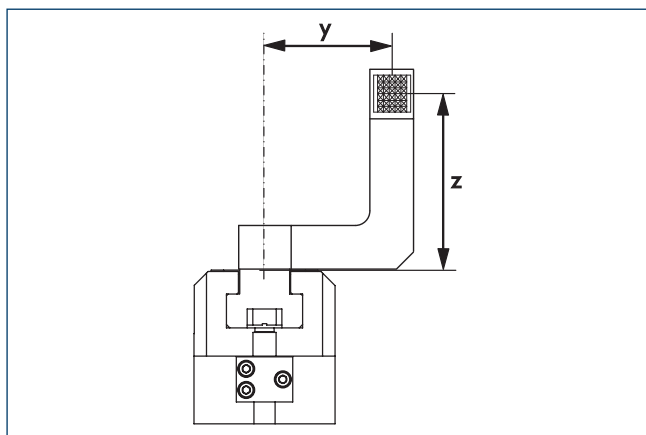
⑦② Fit for centering sleeves

⑧① Depth of the centering sleeve hole in the counter part

⑨① Thread below the cover for fastening external attachments

⑨① Sensor MMS 22..

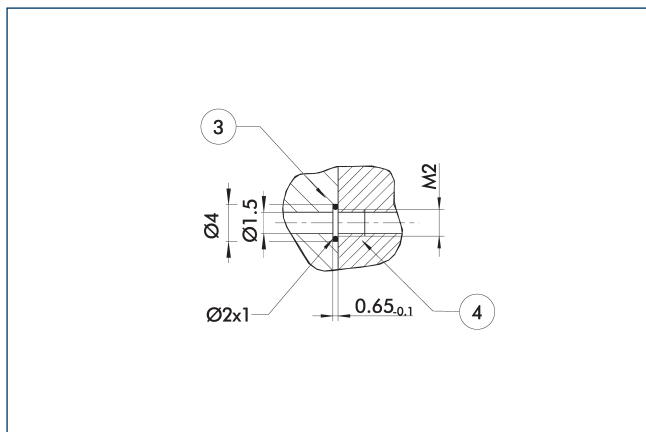
Maximum permitted finger projection



■ Permitted range ■ Inadmissible range

The curve applies for stroke version 1. For other versions, the curve must be parallelly off-set to the max. permissible finger length.

Hose-free direct connection M2

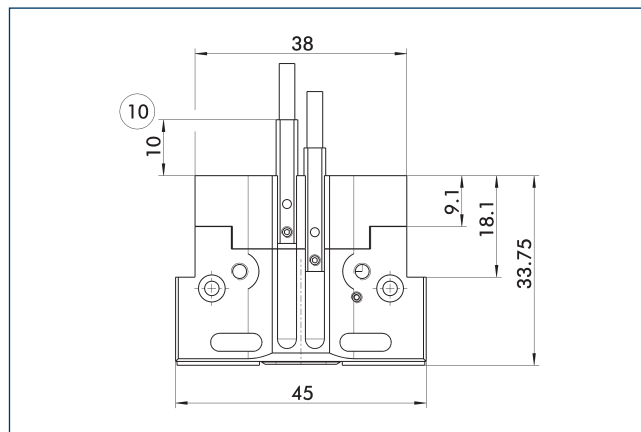


③ Adapter

④ Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

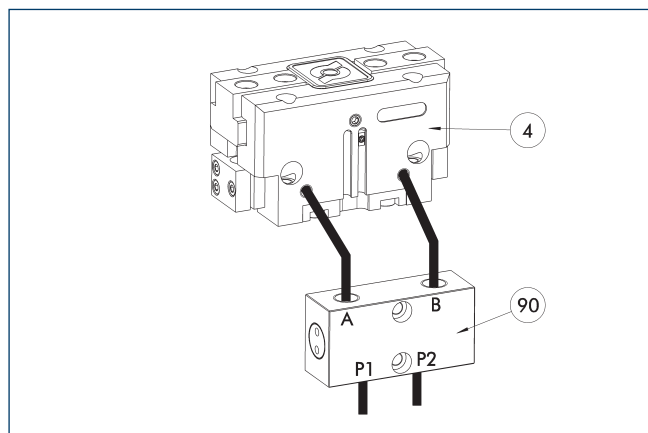
Gripping force maintenance device AS / IS



⑩ Projection applies only for AS version

The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

UZF 40 universal intermediate jaw



- ④ Grippers

[illegible]

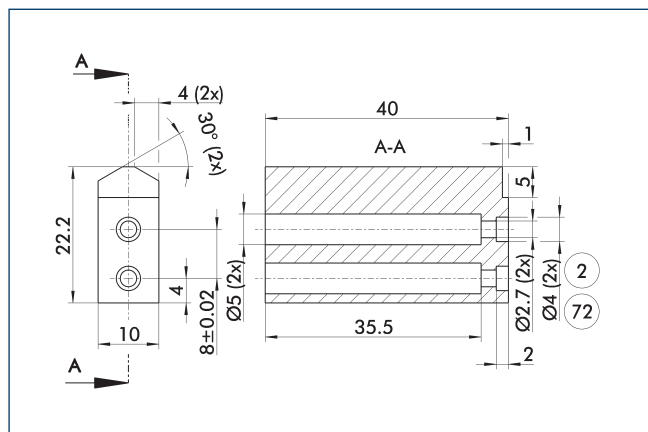
- | | |
|--------------------------------------|---|
| ① Gripper connection | ⑤7 Locking |
| ② Finger connection | ⑦2 Fit for centering sleeves |
| ⑤4 Optional right or left connection | ⑧0 Depth of the centering sleeve hole in the counter part |

Description	ID	Recommended hose diameter [mm]
Pressure maintenance valve		
SDV-P 04	0403130	6
Pressure maintenance valve with air bleed screw		
SDV-P 04-E	0300120	6

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

Description	ID	Grid dimension
		[mm]
Universal intermediate jaw		
UZH 40	0300040	1
Finger blank		
ABR-PGZN-plus 40	0300008	
SBR-PGZN-plus 40	0300018	

Compensation unit AGE-F



- ② Finger connection ⑦② Fit for centering sleeves

- ## 90 Monitoring

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 40	0300008	Aluminum	1
SBR-PGZN-plus 40	0300018	Steel	1

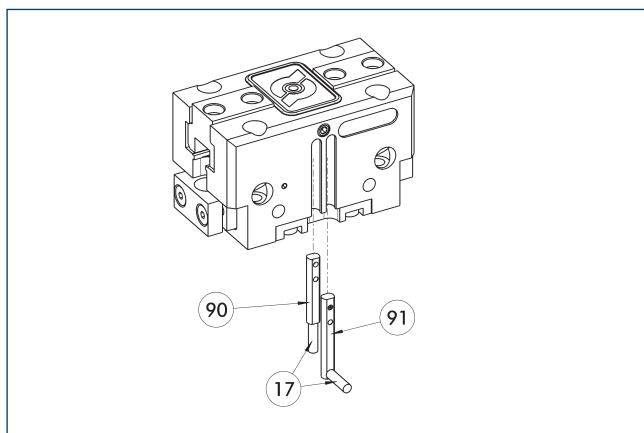
Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-031-1	0324900	± 1.5	1.5	
AGE-F-XY-031-2	0324901	± 1.5	4	
AGE-F-XY-031-3	0324902	± 1.5	5.5	●

- | Description | ID | |
|-----------------|---------|--|
| Tool side | | |
| A-CWA-050-040-P | 0305754 | |

- | Description | ID | Often combined |
|-------------------|---------|----------------|
| Attachment valve | | |
| ABV-MV15-M3 | 0303322 | |
| ABV-MV15-M3-V2-M8 | 0303384 | |
| ABV-MV15-M3-V4-M8 | 0303354 | ● |
| ABV-MV15-M3-V8-M8 | 0303355 | |

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- This diagram shows the front bracket assembly (90) being attached to the main bracket (91). The front bracket (4) is shown in an exploded view, indicating its position relative to the other components. The front bracket (4) has a central rectangular opening and a small protrusion on its side. The main bracket (91) has a large rectangular opening and a series of mounting holes. The front bracket assembly (90) is shown with a small protrusion on its side that fits into the main bracket (91).

Electronic magnetic switch MMS



①⑦ Cable outlet

①⑨ Sensor MMS 22...-SA

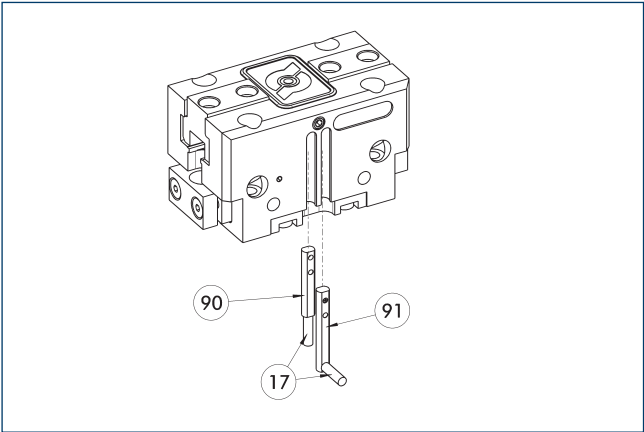
①⑩ Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



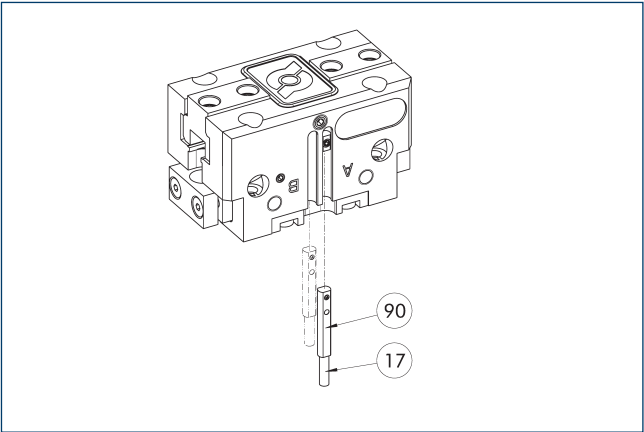
- 17 Cable outlet
- 91 Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI2



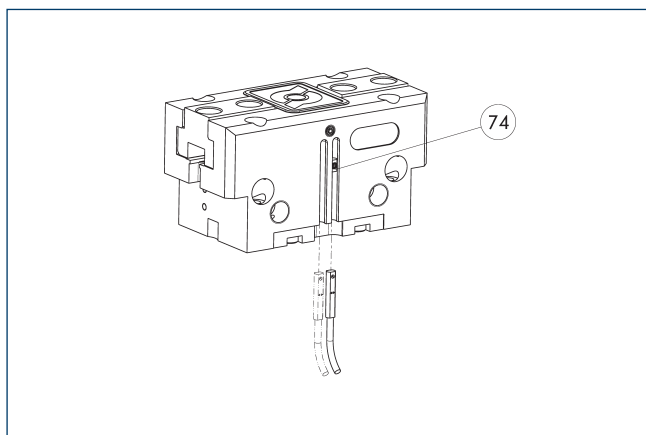
- 17 Cable outlet
- 90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	●
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI2-S-M8-PNP-SA	0301186	●
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI2-S-M8-PNP-HD	0301130	●
MMSK 22-PI2-S-PNP-HD	0301132	

- ① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

MMS-P programmable magnetic switch



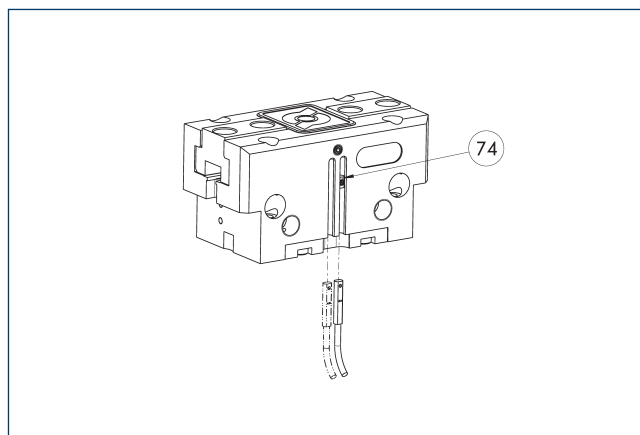
⑦④ Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic switch		
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	●
Connection cables		
KA BG08-L 4P-0500	0307767	●
KA BG08-L 4P-1000	0307768	
KA BW08-L 4P-0500	0307765	
KA BW08-L 4P-1000	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

- ① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-IO-Link



⑦④ Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-IO-L-M08	0315830	
MMS 22-IO-L-M12	0315835	

- ① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.



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